

Climate-Envelope Predictions of Animal Ranges: Model Differences and Model Reliability

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1 **Abstract**

2

3 Predicted changes in the global climate are likely to cause large shifts in the geographic
4 ranges of many plant and animal species. To date, predictions of future range shifts have
5 relied on a variety of modeling approaches with different levels of model accuracy.
6 Using a common data set, we investigated the potential implications of alternative
7 modeling approaches for conclusions about future range shifts and extinctions. Our
8 common data set entailed the current ranges of 100 randomly selected mammal species
9 found in the western hemisphere. Using these range maps, we compared six methods for
10 modeling predicted future ranges. Predicted future distributions differed markedly across
11 the alternative modeling approaches, which in turn resulted in estimates of extinction
12 rates that ranged between 0 and 7%, depending on which model was used. Random
13 forest predictors, a model-averaging approach, consistently outperformed the other
14 techniques (correctly predicting > 99% of current absences and 86% of current
15 presences). We conclude that the types of models used in a study can have dramatic
16 effects on predicted range shifts and extinction rates; and that model-averaging
17 approaches appear to have the greatest potential for predicting range shifts in the face of
18 climate change.

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1 INTRODUCTION

2 Global temperatures have risen an average 0.6°C over the past century (Houghton
3 *et al.*, 2001). Recent studies suggest that this climate change has caused shifts in the
4 geographic ranges of both plants and animals (Parmesan & Yohe, 2003; Root *et al.*,
5 2003). Given that average global temperatures are predicted to rise between 1.4°C and
6 5.8°C over the next century (Houghton *et al.*, 2001), it is likely that many species will
7 undergo dramatic range shifts in the future. To anticipate the effects of climate change,
8 and to identify conservation strategies that might mitigate the undesirable consequences
9 of climate change, it is essential that we develop models that link the distributions of
10 species to alternative scenarios of climate change.

11 Several studies have attempted to predict future range shifts, often with the goal
12 of estimating climate-induced extinction rates (Williams *et al.*, 2003; Thomas *et al.*,
13 2004). Most predictions of future species distributions rely on what are commonly called
14 climate-envelope models. These models attempt to relate species geographic
15 distributions to a set of climatic factors. Relatively simple climate variables are used to
16 define the abiotic conditions, or “climate envelope” in which a species exists. Predicted
17 future climate variables, usually derived from a general circulation model (GCM), are
18 used as input for these models to predict future distributions. Unfortunately, researchers
19 have reported large uncertainties and error rates in these climate-envelope predictions,
20 and we have little understanding of which, if any of these modeling approaches is most
21 reliable (Segurado & Araújo, 2004; Thuiller, 2003).

22 In this paper, we report on a systematic comparison of all the major approaches to
23 predicting range shifts with a common data set and common metrics for estimating error

1 rates. Our goal was to quantify the types of errors associated with range-shift models and
2 to determine whether any approach clearly outperforms the alternatives. The approaches
3 we examined were: generalized linear models (McCullagh & Nelder, 1989), classification
4 trees (Breiman *et al.*, 1984), generalized additive models (Hastie & Tibshirani, 1990),
5 random forest predictors (Breiman, 2001), artificial neural networks (Ripley, 1996), and
6 genetic algorithms for rule-set prediction (GARP, Peterson *et al.*, 2002).

7

8 METHODS

9 We compared the model accuracy and the future predictions of the six different
10 modeling approaches described below by applying each approach to 100 randomly
11 selected mammal species in the western hemisphere. All analyses were conducted on a
12 50x50-km resolution grid consisting of 15,323 cells. Current species distributions were
13 based on digital range maps (Patterson *et al.*, 2003). We selected the 100 species at
14 random from 1,022 mammals with ranges occupying at least 50 grid cells.

15 Current climate data were derived from average monthly precipitation and
16 temperature values from 1961-90 for the land surface of the globe at 0.5° resolution
17 (Leemans & Cramer, 1991). For that 30-year period, we calculated mean annual
18 temperature, average temperature of the hottest and coldest months, and degree-days over
19 5°C. We also calculated average yearly precipitation as well as precipitation in the
20 hottest, coldest, wettest, and driest months.

21 Current land cover was derived from both predicted current potential vegetation
22 and measured land cover derived from Advanced Very High Resolution Radiometer
23 (AVHRR) satellite data (Loveland *et al.*, 1999). Predicted current vegetation types were

1 produced using the Mapped Atmospheric-Plant-Soil System (MAPSS) model (Neilson,
2 1995). Although measured vegetation provides a more accurate representation of current
3 vegetation, we chose to use the predicted current vegetation to best correspond with the
4 classification of predicted future vegetation for the years 2061-2090. MAPSS predictions
5 of current potential vegetation have been shown to closely approximate other potential
6 vegetation classifications (Bachelet *et al.*, 2001). We overlaid the 44 land-cover classes
7 of predicted potential current vegetation from the MAPSS model with five agriculture
8 classes and one urban and suburban land-cover class from the AVHRR-derived land-
9 cover data to produce the new 50-class land-cover data set used for building the models.

10 Predicted future climate data were produced using the Hadley Climate Centre's
11 HADCM2SUL model (Johns *et al.*, 1997) using Intergovernmental Panel on Climate
12 Change (IPCC) predicted future greenhouse gas contributions (IS92a) for the years 2061-
13 2090 (Kattenberg *et al.*, 1996). This model and greenhouse gas contribution scenario
14 together generally predict larger increases in precipitation and smaller increases in
15 temperature (particularly for North America) than do more recent models. Although a
16 wide array of more recent GCM predictions based on alternative emissions scenarios
17 exist, the purpose of our study was not to draw conclusions about the future, but to
18 compare the differences in predictions resulting from using different climate-envelope
19 modeling approaches. Using the future climatic predictions, we calculated the same set
20 of nine climate variables for all 0.5° grid cells. Predicted future land cover was produced
21 with the MAPSS model using the predicted climate data for input. For the purposes of
22 these analyses, we assumed no change in the distribution of agriculture and urban-
23 suburban areas. We overlaid the predicted future potential vegetation data with the

1 current agriculture and urban-suburban data to produce predicted future land cover. All
2 data compiled at 0.5° resolution were projected to the 50-km resolution grid.

3

4 Modeling Approaches

5 For all six modeling approaches, we used the presence and absence of a species as
6 the response variable and the set of nine continuous variables representing current climate
7 and one categorical variable representing the 50 land-cover classes as predictors. All
8 models except the GARP models were built using the R software package (version 1.9.1).
9 For all 100 species, we selected a training- and a test-data set. For the training set, we
10 randomly selected 80% of all species presences and 80% of all species absences. For
11 each species, we then used the remaining 20% of the data for testing the models and
12 determining their errors in terms of absences falsely predicted as presences (commission
13 error), and presences falsely predicted to be absences (omission error).

14

15 *Generalized Linear Models*

16 Generalized linear models offer a slightly more flexible modeling framework than
17 basic linear regression models as they allow for the modeling of alternative distributions
18 in the response variable and non-constant variance functions (Guisan *et al.*, 2002). We
19 built logistic regression models (generalized linear models with an assumed binomial
20 error distribution) using a combined backward- and forward-stepwise selection process.
21 Variable inclusion was based on Akaike's information criterion (Chambers & Hastie,
22 1991). We modeled all linear and second order polynomials of the climatic predictor
23 variables. Because the test-data sets for 21 species contained land-cover classes that were

1 not found in the training sets of those species, we chose to drop the land-cover variable
2 from the models for these species.

3

4 *Classification Tree Models*

5 Classification trees, and regression trees, their counterpart for analyzing
6 continuous response variables, are non-parametric modeling approaches (Venables &
7 Ripley, 2002; Breiman *et al.*, 1984). Both techniques involve the recursive binary
8 partitioning of data. Each split of the data is made using the predictor variable and the
9 point along that variable's distribution that divides the data into the two most
10 homogeneous groups with respect to the response variable. The result is a tree like-
11 structure with one root node and a number of terminal nodes. In a classification tree, the
12 proportional class-membership of the observations in a terminal node form the basis for
13 predicted probabilities. De'ath and Fabricius (2000) provide excellent examples of the
14 use of tree-based models for ecological analyses. We fit classification trees using the
15 RPART package in R originally designed for S-Plus (Therneau & Atkinson, 1997).
16 Because most trees tend to over-fit the data, we selected the optimal tree size using the
17 modal size suggested by 50 10-fold cross-validations applying a 1-SE rule (De'ath &
18 Fabricius, 2000).

19

20 *Generalized Additive Models*

21 Generalized additive models (GAM) are similar to generalized linear models, but
22 they are more flexible because they do not require a specific response curve to be fit to
23 the predictor variables (Hastie & Tibshirani, 1990). Smoothing functions allow data-

1 driven response curves to be fit for each predictor variable. We fit generalized additive
2 models using penalized regression splines (Wood & Augustin, 2002). This approach
3 takes advantage of generalized spline smoothing (Wahba, 1990) but can be equally or
4 less computationally expensive than backfit GAMs. To increase the speed of the
5 modeling process, we pre-screened each variable by fitting a GAM model for that
6 variable alone. We dropped all variables for which the fitting algorithm was unable to
7 converge. Variable selection for those variables included in the modeling process was
8 based on smoothness penalties in conjunction with a shrinkage parameter. Variables
9 were effectively dropped from a model based on the fit smoothing parameter. We used
10 the MGCV package in R to fit all GAM models (Wood & Augustin, 2002). As for the
11 generalized linear models, we did not include the categorical land-cover variable in the
12 models built for the 21 species for which the test-data set contained land-cover classes
13 not found in the training-data set.

14

15 *Random Forest Predictors*

16 Random forest predictors are a model-averaging approach based on regression or
17 classification trees (Breiman, 2001). Instead of building one tree model, the random
18 forest algorithm builds multiple trees using randomly selected subsets of the observations
19 and random subsets of the predictor variables. The predictions from the trees are then
20 averaged (in the case of regression trees) or tallied using a voting system (for
21 classification trees). We used the R package RandomForest to build random forest
22 predictors. As part of the random forest procedure, 500 classification trees were built for
23 each species. To build each tree, 12,258 observations were selected at random, with

1 replacement, from the training set. For each split in these trees, three predictor variables
2 were selected at random from the full set of 10 predictor variables as candidates for that
3 particular split.

4

5 *Artificial Neural Networks*

6 Artificial neural networks are a machine-learning approach based on real neural
7 networks (Ripley, 1996). The networks are composed of a series of interconnected nodes
8 (neurons) which receive and process input signals and potentially generate output signals.
9 A network is trained on a data set to recognize the patterns in the data. We built artificial
10 neural networks using the NNET package in R which was based on the S-Plus package
11 NNETW (Venables & Ripley, 2002). These feed-forward networks had one hidden layer
12 with eight nodes. To train the network, we used 5000 presence and 5000 absence
13 observations selected at random, with replacement, from the training-data set. Trial and
14 error determined that these 10,000-observation data sets were most effective and efficient
15 for training the networks. To produce more robust predictions, we built 10 networks for
16 each species and averaged the model predictions (Thuiller, 2003; Segurado & Araújo,
17 2004).

18

19 *Genetic Algorithms for Rule-Set Prediction*

20 GARP is a machine learning-based approach that uses a genetic algorithm (a
21 stochastic optimization technique) to assemble a set of rules to define a species' range
22 (Stockwell & Noble, 1992). The approach was developed expressly for predicting
23 species distributions. The rules used by the GARP algorithm include logistic

1 relationships, climate envelopes (Nix, 1986), and simple Boolean rules. We used the
2 Unix version of GARP to build 500 models for each species. All models were selected
3 from all rule-types. GARP limits model training sets to 2500 observations. For each of
4 the 500 models, we selected 1250 presences and 1250 absences, with replacement, from
5 the training-data set for the given species. For each species, we used Cohen's Kappa
6 statistic (Monserud & Leemans, 1992), calculated using the training-data set, to select the
7 10 best performing models from the set of 500 models. We combined the binary
8 predictions of these 10 models to produce a predicted probability of presence.

9

10 Model Comparisons

11 Using the reserved test-data set, we computed four different metrics to compare
12 the performance of the six different modeling approaches. The first three of these
13 approaches included the percentage of the presences correctly classified, the percentage
14 of the absences correctly classified, and Cohen's Kappa. Because all six modeling
15 approaches produced predicted probabilities, calculating these three metrics required
16 selecting a threshold with which to classify predicted presences and absences. We used
17 receiver-operating characteristic (ROC) curves to select the optimal threshold, assuming
18 that predicting presences correctly was twice as important as predicting absences
19 correctly (Fielding & Bell, 1997). This is a conservative approach and should generally
20 reduce the chances of overestimating future range contractions. In addition to the three
21 metrics listed above, we used the area under the ROC curve (AUC) to provide an
22 assessment of model performance that was independent of a specific classification
23 threshold (Fielding & Bell, 1997). We compared model performance across model types

1 using Wilcoxon's signed-ranks tests with a Holm correction for conducting multiple tests
2 (Holm, 1979).

3

4 Future Predictions

5 We used the models to predict future geographic ranges under two alternative
6 dispersal scenarios. First, we assumed that a species would be able to completely
7 disperse into any new geographic range. For the second scenario, we assumed that a
8 species would be unable to disperse from its current range. These two extreme
9 assumptions have been made in several recent studies with which we wish to draw
10 comparisons (Peterson *et al.*, 2002; Thomas *et al.*, 2004). Realistic future range shifts are
11 likely to fall somewhere between these two extremes.

12

13 RESULTS

14 How did alternative modeling approaches affect the types of error and uncertainty
15 in our analyses? The amounts and types of error were markedly influenced by which
16 approach was used to predict range shifts (Table 1). The most significant consistencies in
17 model performance were the over-prediction of current presences (commission error) by
18 the neural networks and GARP models, the under-prediction of current presences
19 (omission error) by the classification tree models, and the small number of errors
20 predicted by the random forest models. For example, classification trees often incorrectly
21 predicted current presences (median of 56% correct). This is a higher rate of omission
22 error than produced by the other five approaches (medians of 69% to 86% correct
23 presences). GARP models tended to have higher commission error rates than the other

1 approaches, correctly predicting 96% of test-set absences compared to correct prediction
2 rates of between 98% and 100% of absences for the other types of models. The spatial
3 patterns of both commission and omission errors also differed across the six modeling
4 approaches (e.g., Fig. 1). Whereas the commission errors of the GARP models and
5 artificial neural networks tended to be relatively widely distributed, the few errors that the
6 random forest models produced were generally clustered tightly around the area occupied
7 by the species (Fig. 1).

8 We also found that different modeling approaches produced dramatically
9 different predictions of future range shifts for many species. Not surprisingly, these
10 differences were heavily influenced by assumptions regarding dispersal. On average, if
11 one assumes no dispersal, so that species cannot move to occupy newly created favorable
12 “climate space”, only 19% of the cumulative future range of a species was similarly
13 predicted by all six models. The percent agreement was even lower (11%) when full
14 dispersal (species can fully exploit new favorable climate space that arises in the future)
15 was assumed. For example, for the black tufted-ear marmoset (*Callithrix penicillata*),
16 assuming unlimited dispersal, the generalized linear model and classification tree
17 predicted contractions of 70% and 58% of the current range, respectively, whereas the
18 artificial neural network and the GARP model respectively predicted expansions of 180%
19 and 53% of the range (Fig. 2). These differences translated into different estimates of
20 overall range contractions and extinction rates as predicted by the alternative modeling
21 approaches (Fig. 3). When we assumed unlimited dispersal, classification trees predicted
22 range contractions of over 50% for 36% of the species in the study compared to neural
23 networks and GARP models which respectively predicted similar range contractions for

1 16% and 17% of all species. Because these models are often used to predict extinction
2 rates, it is worth noting that depending on the modeling approach used, extinction rates
3 ranged from 0% to 7% assuming unlimited dispersal and from 6% to 14% assuming no
4 dispersal.

5 All of the differences among models would be daunting were it not for the finding
6 that one modeling approach clearly performed better than all of the alternatives. In
7 particular, random forest models had the highest median performance scores across all
8 four measures of model accuracy (Table 1), and were consistently ranked the best
9 performing of the six model types (Fig. 4). Random forests were the best performing
10 models with respect to AUC and Kappa for 88% of species.

11

12 DISCUSSION

13 There are several different approaches to predicting changes in species
14 distributions as a result of climate change (Thomas *et al.*, 2004; Meynecke, 2004; Iversen
15 & Prasad, 1998; Araújo *et al.*, 2004; Pearson *et al.*, 2002; Shafer *et al.*, 2001). With few
16 exceptions, previous studies have found very little consistency in the performance of
17 these alternative approaches (Moisen & Frescino, 2002; Thuiller, 2003; Robertson *et al.*,
18 2003; Segurado & Araújo, 2004). We have found similar inconsistency among models,
19 but are able to understand why these differences arise. The six modeling techniques that
20 we applied make different assumptions about the relationships between species and their
21 environments (Guisan & Zimmermann, 2000). Because different species can have
22 qualitatively different relationships with their environments, many modeling approaches
23 work differently for different groups of species (Segurado & Araújo, 2004). For

1 example, generalized linear models assume a given response curve that defines the
2 relationship between the probability of presence and various environmental gradients.
3 These models will generally work well for species with relatively simple relationships to
4 environmental gradients. The other five techniques that we tested are more flexible with
5 respect to the complexity of the relationships that they can model. For example,
6 generalized additive models allow for complex relationships with individual variables to
7 be modeled. They are not, however, as adept at modeling complex interactions between
8 variables as are classification tree models or random forests. Artificial neural networks
9 and GARP models, the two machine-learning based approaches tested here, are in part an
10 attempt to model both complex relationships with individual variables and complex
11 interactions among those variables.

12 This inconsistency among range shift models has led some to suggest innovative
13 methods for addressing model uncertainty in the prediction of future range shifts
14 (Thuiller, 2003; Thuiller *et al.*, 2004). Another approach to reducing uncertainty is to ask
15 whether some models might simply perform better than others, and hence we need not
16 consider all of their predictions. Pursuing that strategy, our study compares essentially
17 the full suite of climate-envelope approaches with a common data set, several metrics of
18 model performance, and alternative assumptions about dispersal. The lessons are clear.
19 First, random forest predictors, which averaged the predictions of hundreds of models,
20 were consistently the best performers, and for the data we examined, performed
21 remarkably well. They achieved error rates of less than 15% for presences and less than
22 1% for absences. We are aware of only one other study that has compared the
23 performance of random forest predictors to other models for use as climate-envelope

1 models. Prasad *et al.* (in press) found that random forest models and bagging (another
2 tree-based model-averaging approach) consistently produced better predictions than
3 multivariate adaptive regression splines and regression trees for predicting the
4 distributions of four tree species. The performance of each of the other five modeling
5 approaches tested here, but not by Prasad *et al.*, is generally comparable to the
6 performance of models of the same type tested elsewhere (Thuiller *et al.*, 2003; Pearson
7 *et al.*, 2004; Segurado & Araújo, 2004).

8 Our results raise the obvious question of why random forest models work so
9 remarkably well. The strength of this approach likely lies in the power derived from
10 averaging hundreds of different models (Breiman, 2001). The individual models are built
11 with randomly selected subsets of the data and randomly selected subsets of the predictor
12 variables. Although we averaged 10 artificial neural networks and 10 GARP models to
13 produce predictions for each species, the model averaging accomplished by random
14 forest predictors is much more comprehensive. Although it is possible that model-
15 averaging applied similarly to techniques other than the classification trees on which
16 random forests are based would produce models of comparable accuracy, the tree-based
17 models themselves provide added advantages over other modeling approaches. In
18 addition to providing a method for modeling complex interactions without having to
19 specify them *a priori*, tree-based models allow the relationships between the response
20 and the predictors to vary over the domain of the study. This is particularly advantageous
21 for modeling data that cover large and diverse geographic areas.

22 The second lesson to be taken from our study is that the different modeling
23 approaches tend to be relatively consistent in the types of errors they make. For example,

1 classification trees produced the most omission errors whereas GARP models had the
2 highest commission error rates. These errors, in turn, lead to different predicted range
3 shifts, extinction rates, and changes in species composition at specific sites. Although
4 there is no assurance that the model that best fits the current data will be the best model
5 for predicting future distributions, it is likely that minimizing known errors in the current
6 predictions will reduce the total amount of error in future predictions.

7 Lastly, the models differed greatly in the extent to which they predicted shrinking
8 ranges versus expanding ranges in the face of climate change. For example, when we
9 assumed unlimited dispersal, classification tree models predicted extinctions for 7% of
10 the species compared to GARP models, which predicted no extinctions. Similarly,
11 Thuiller *et al.* (2004) demonstrated potential differences in predicted extinction rates
12 across modeling approaches ranging from less than 1% to roughly 5% over a 50 year
13 period. The uncertainties in future range predictions that can be attributed to the errors in
14 the climate-envelope models currently in use are likely to be greater than the
15 uncertainties of actually predicting the underlying climate change (i.e., the differences
16 among climate models and emissions scenarios) (Thuiller, 2004). This means that unless
17 we can produce more accurate range shift models, they cannot really be used to compare
18 the consequences of different carbon emissions scenarios. Looking forward, it appears
19 that random forest models or other model-averaging approaches may yield robust
20 predictions of range shifts in the face of climate change. It will still be difficult to
21 translate these predictions into expected extinctions and species turn-over rates because
22 actual range shifts will depend on dispersal, evolutionary flexibility, and species
23 interactions. Nonetheless, for the sake of adaptive management and conservation

1 planning, random forest models provide a useful and reliable tool. By minimizing the
2 uncertainty in climate-envelope models, studies of climate-induced range shifts can
3 concentrate on elucidating the effects of the more important uncertainties in climate-
4 change predictions.

5

6

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- 16

1 Table 1. Accuracy of six different modeling approaches used to model the current
 2 geographic ranges of 100 mammal species in the western hemisphere. Accuracy was
 3 assessed using a reserved test-data set composed of a randomly selected 20% of the
 4 presences and 20% of the absences for each species. Values reported are the medians and
 5 one half of the inter-quartile range of the accuracy of the model predictions for 100
 6 species. Values with the same letters were not significantly different ($P > 0.05$).
 7

Model*	% presences	% absences	Kappa	AUC [†]
	correct	correct		
GLM	77.7 (17.3), a	98.9 (1.4), a	0.68 (0.13), a	0.970 (0.017), a
TREE	55.5 (19.0), b	99.6 (0.5), b	0.63 (0.13), b, c	0.838 (0.072), b
GAM	68.9 (19.3), a	99.1 (1.4), a	0.62 (0.15), a, b	0.966 (0.022), c, d
RF	86.0 (12.1), c	99.6 (0.3), c	0.86 (0.09), d	0.995 (0.003), e
ANN	75.6 (12.5), a	98.2 (2.1), d	0.58 (0.13), c, e	0.968 (0.017), a, c
GARP	85.0 (6.2), c	95.9 (2.7), e	0.53 (0.17), e	0.962 (0.023), d

8 * Model abbreviations: GLM, generalized linear model; TREE, classification tree; GAM,
 9 generalized additive model; RF, random forest; ANN, artificial neural network; GARP,
 10 genetic algorithm for rule-set prediction.

11 † AUC is the area under the receiver-operating characteristic curve.

12

13

14

15

1 FIGURE LEGENDS

2

3 Figure 1. Maps of the current range of the black tufted-ear marmoset (*Callithrix*
4 *penicillata*) as predicted by six alternative modeling approaches. See Table 1 for an
5 explanation of model abbreviations.

6

7 Figure 2. Maps of the predicted future range of the black tufted-ear marmoset (*Callithrix*
8 *penicillata*) as predicted by six alternative modeling approaches. See Table 1 for an
9 explanation of model abbreviations.

10

11 Figure 3. Climate-induced range contractions for 100 species as predicted by six
12 different modeling approaches. We report the percentage of species predicted to
13 experience each of three levels of range contraction when A) individuals are assumed to
14 be able to disperse completely into their future range and B) individuals cannot disperse
15 out of their current range.

16

17 Figure 4. Ranking of the performance of six different modeling approaches for
18 predicting the current distribution of 100 mammal species. Performance was assessed as
19 A) the percentage of correctly predicted presences, B) the percentage of correctly
20 predicted absences, C) the Kappa statistic, and D) the area under the receiver-operating
21 characteristic curve (AUC). Each set of box and whiskers represents the median, first
22 and third quartiles, and the maximum and minimum values. See Table 1 for an
23 explanation of model abbreviations.

Figure 1

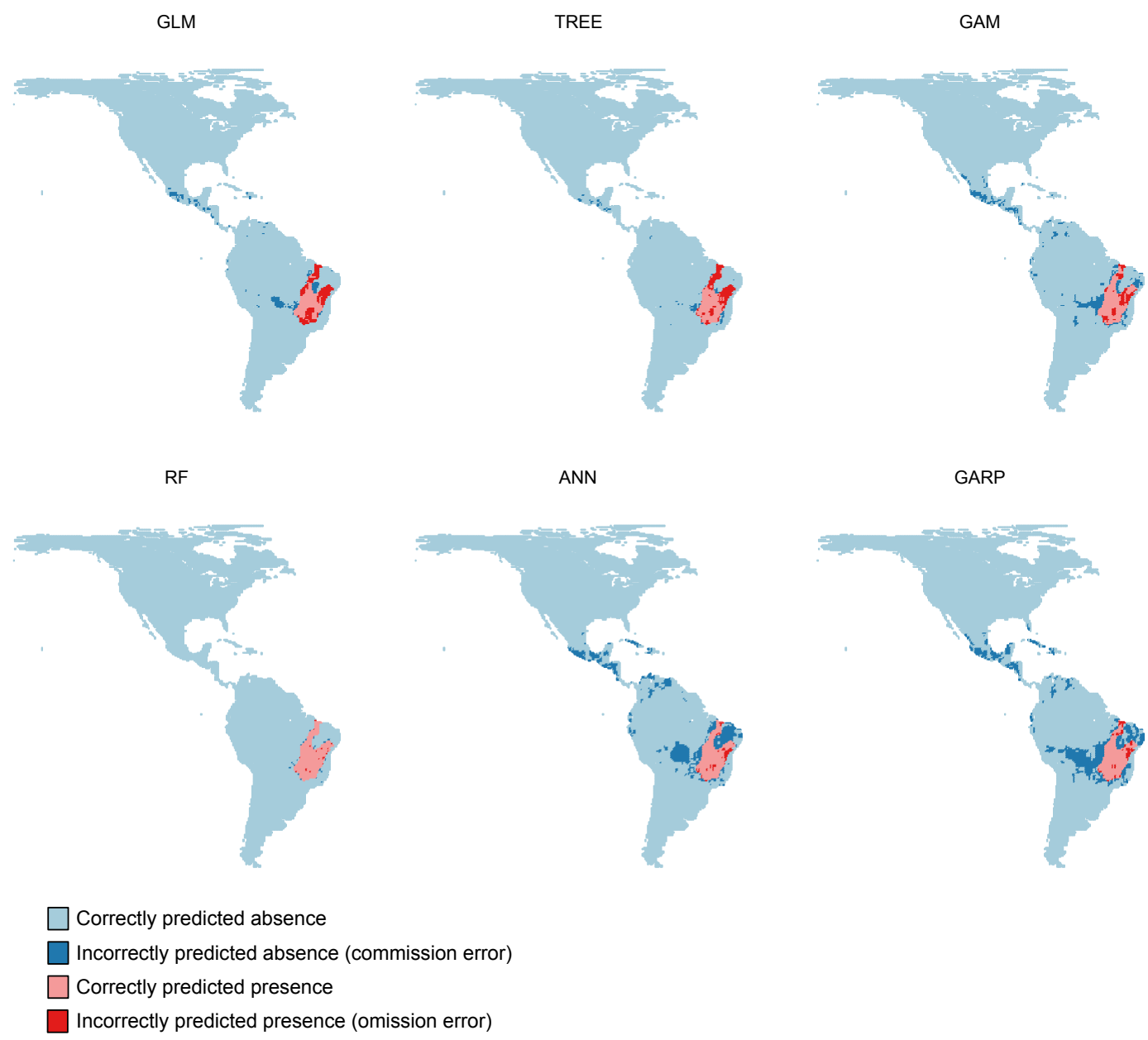


Figure 2

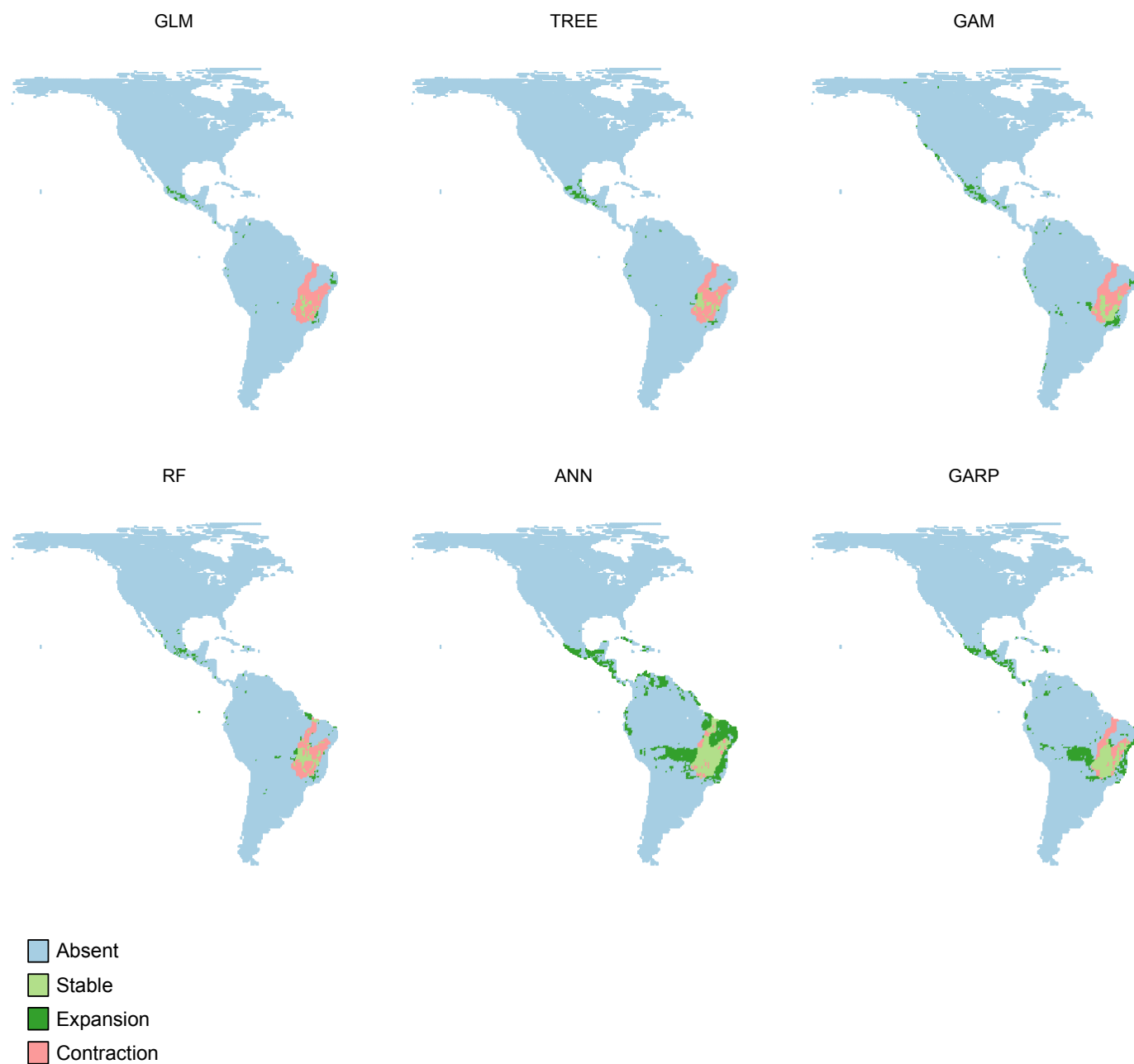


Figure 3

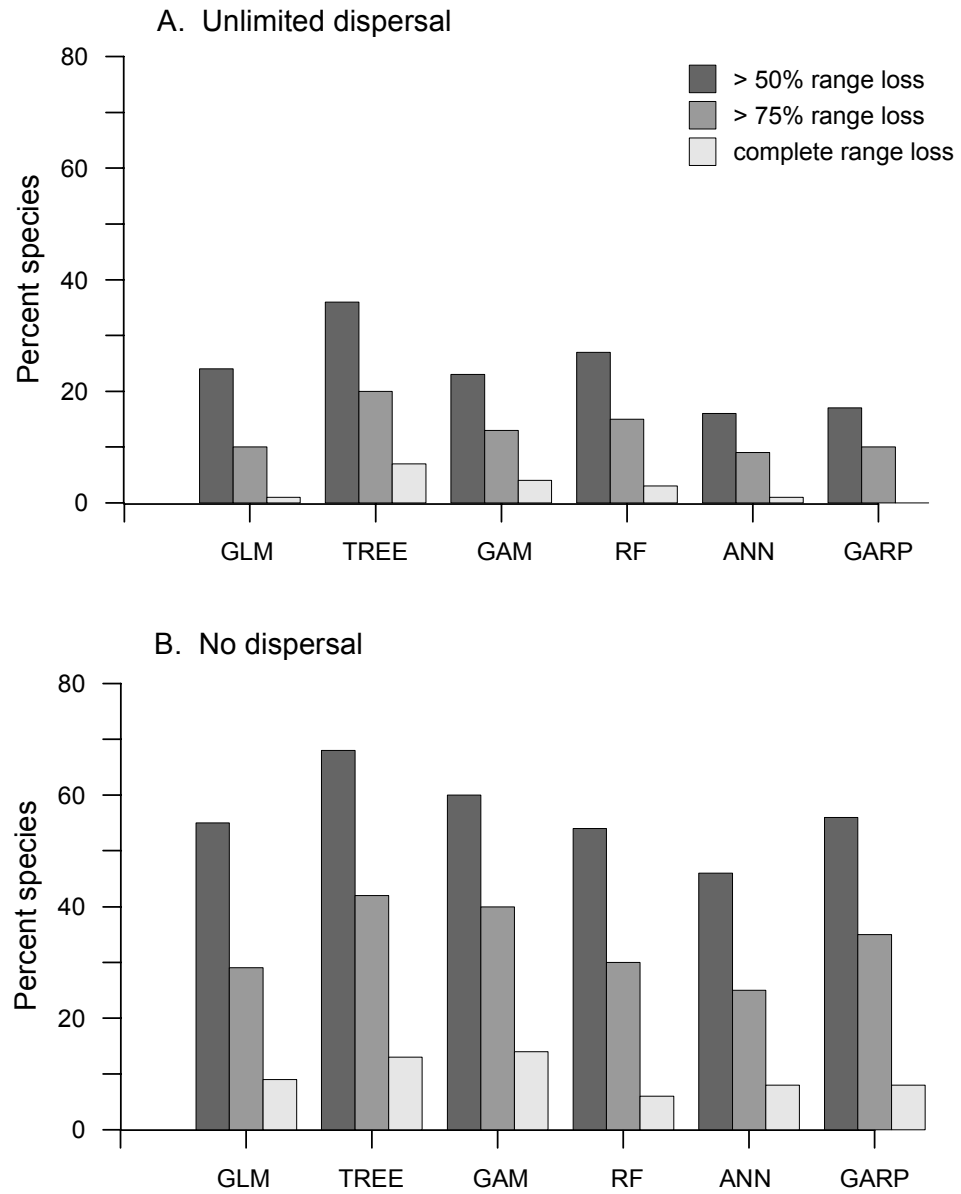
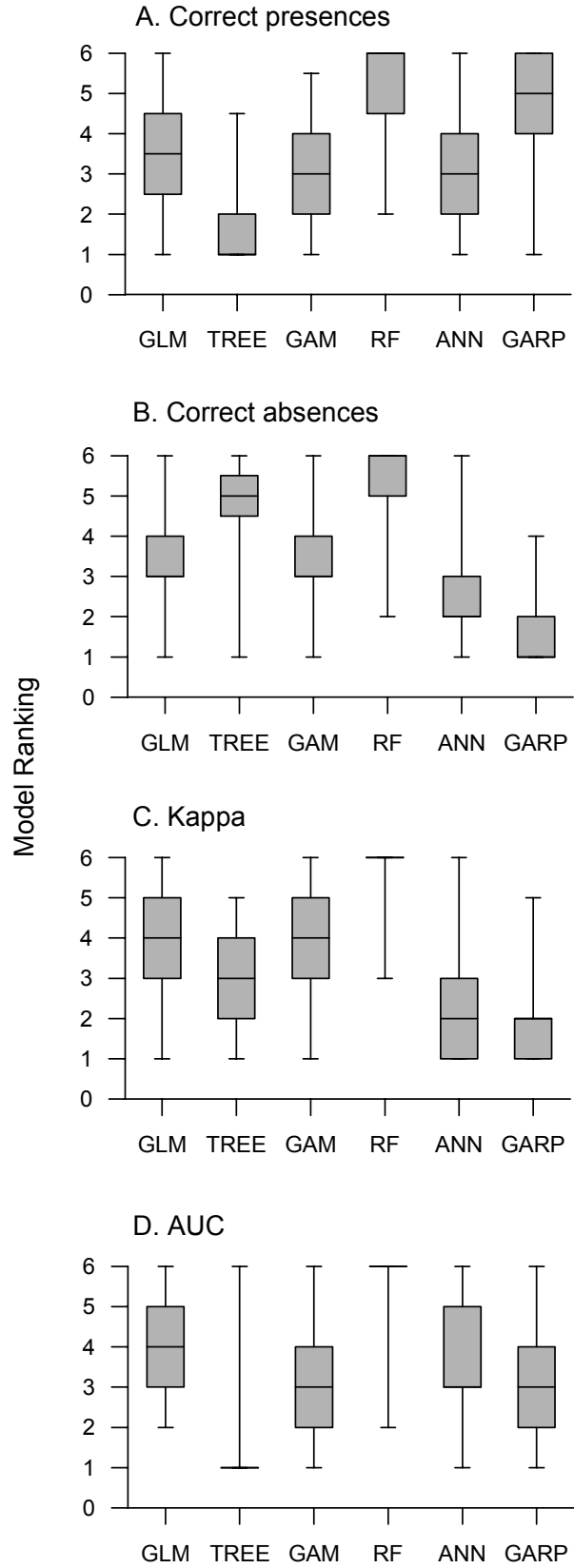


Figure 4



Appendix. Future predicted range sizes of 100 mammal species in the western hemisphere as a proportion of current range. Future ranges were predicted using six different modeling approaches given two different dispersal scenarios. The models included generalized linear models (GLM), classification trees (TREE), generalized additive models (GAM), random forest predictors (RF), artificial neural networks (ANN), and genetic algorithms for rule-set prediction (GARP). The dispersal scenarios assumed that individuals could disperse completely into the predicted new range (unlimited dispersal) or conversely, that they were restricted to areas in which the current and future predicted ranges overlapped (no dispersal).

Scientific name	English name	Current range (km ²)	Predicted future range as a proportion of current range											
			Unlimited dispersal						No dispersal					
			GLM	TREE	GAM	RF	ANN	GARP	GLM	TREE	GAM	RF	ANN	GARP
<i>Akodon albiventer</i>	White-bellied Grass Mouse	437500	0.51	0.55	1.03	1.58	0.92	1.71	0.34	0.31	0.54	0.68	0.46	0.68
<i>Akodon cursor</i>	Cursor Grass Mouse	1430000	0.64	0.21	0	0.53	1.06	0.38	0.39	0.17	0	0.29	0.31	0.17
<i>Alouatta caraya</i>	Black Howling Monkey	3127500	1.08	0.34	0.79	0.31	0.97	0.62	0.41	0.19	0.23	0.17	0.58	0.25
<i>Alouatta pigra</i>	Black Howling Monkey	275000	5.71	0.45	0.75	4.48	1.51	3.61	0.54	0.05	0.03	0.04	0.06	0.21
<i>Alouatta sara</i>	Bolivian Red Howling Monkey	410000	7.03	0.15	3.85	1.27	10.09	1.07	0	0	0	0.12	0.71	0.37
<i>Amorphochilus schnablii</i>	Smoky Bat	370000	0.88	0.09	0.92	1.01	1.01	2.91	0.37	0.07	0.43	0.36	0.34	0.68
<i>Anoura latidens</i>	Broad-toothed Tailless Bat	1417500	2.75	3.29	7.13	7.39	0.33	5.35	0.64	0.57	0.81	0.82	0.12	0.63
<i>Aotus vociferans</i>	Tropical Night Monkey	1157500	1.35	0.05	0.19	0.28	1.67	0.91	0.73	0.01	0	0.08	0.83	0.55
<i>Artibeus fraterculus</i>	Fraternal Fruit-eating Bat	297500	0.84	0.29	0.87	0.33	1.28	1.81	0.19	0.11	0.29	0.18	0.44	0.3
<i>Auliscomys pictus</i>	Painted Big-eared Mouse	320000	0.8	0.18	1.16	0.73	0.82	0.96	0.39	0.13	0.38	0.45	0.39	0.45
<i>Blastocerus dichotomus</i>	Marsh Deer	2005000	1.56	0.5	1.49	0.77	0.9	1.01	0.39	0.22	0.26	0.21	0.44	0.15
<i>Bradypus torquatus</i>	Maned Three-toed Sloth	162500	0.14	0.38	0.02	0.14	0.46	0.51	0	0	0	0	0	0.02
<i>Cabreramops aequatorianus</i>	Equatorial Dog-faced Bat	127500	2.37	0.39	0.16	0.08	1.24	2.53	0.29	0.12	0	0.06	0.14	0.25
<i>Callicebus moloch</i>	Titi Monkey	975000	0.02	0.01	3.64	0.03	1.05	0.02	0	0	0	0	0.31	0
<i>Callicebus nigrifrons</i>	Black-fronted Titi	472500	0.49	0.22	2.58	0.25	1.15	0.04	0.32	0.04	0.15	0.05	0.28	0
<i>Callicebus personatus</i>	Northern Masked Titi	175000	0.11	0.11	0.09	0.06	0.37	0.73	0.01	0.03	0	0.01	0	0.01
<i>Callicebus regulus</i>	Titi Monkey	230000	0	0.03	0	0.04	0.08	0.01	0	0	0	0.04	0.04	0
<i>Callicebus torquatus</i>	Collared Titi	265000	0.17	0.03	0.01	0	8.93	0.03	0.01	0	0	0	0.93	0
<i>Callithrix penicillata</i>	Black Tufted-ear Marmoset	1602500	0.3	0.42	0.71	0.54	2.8	1.53	0.14	0.2	0.28	0.29	0.85	0.56
<i>Cavia aperea</i>	Brazilian Guinea Pig	5725000	0.57	0.77	0.62	0.53	0.78	1.04	0.4	0.49	0.4	0.43	0.58	0.65
<i>Cavia magna</i>	Greater Guinea Pig	172500	0.29	0	0.38	0	0.19	0.87	0.12	0	0.07	0	0.06	0.23
<i>Centronycteris centralis</i>	Bat	1242500	1.42	4.55	7.32	6.34	0.31	3.2	0.3	0.41	0.71	0.77	0.16	0.44
<i>Chinchilla lanigera</i>	Chinchilla	205000	1.06	0.32	0.7	0.44	0.6	2.05	0.63	0.26	0.59	0.43	0.46	0.73
<i>Chinchillula sahamae</i>	Altiplano Chinchilla Mouse	267500	1.08	0.29	1.65	0.59	1.19	1.8	0.55	0.15	0.63	0.36	0.58	0.73
<i>Chiroderma trinitatum</i>	Little Big-eyed Bat	9347500	1.15	1.07	1.07	1.12	0.99	0.7	0.95	0.86	0.87	0.86	0.87	0.66
<i>Chiropotes albinasus</i>	White-nosed Bearded Saki	145000	3.16	1.1	0.07	0.48	10.74	1.12	0.78	0.17	0.07	0.28	0.76	0
<i>Chiropotes albinasus</i>	White-nosed Bearded Saki	1107500	0.31	0.63	0.26	0.32	0.89	0.02	0.14	0.17	0.11	0.06	0.24	0
<i>Chrotopterus auritus</i>	Big-eared Woolly Bat	9182500	1.33	1.49	1.63	1.47	1.71	0.97	0.88	0.92	0.98	0.94	0.98	0.6
<i>Coendou bicolor</i>	Bicolor-spined Porcupine	1237500	0.42	0.73	0.67	3.95	1.72	1.02	0.13	0.22	0.22	0.67	0.58	0.21

<i>Cryptotis mayensis</i>	Maya Small-eared Shrew	147500	0.78	0.78	1.34	0.29	10.59	0.17	0	0	0	0	0.66	0
<i>Ctenomys torquatus</i>	Collared Tucú-tucú	475000	1.1	0.64	0.26	0.59	0.86	0.74	0.6	0.39	0.06	0.39	0.24	0.28
<i>Cyclopes didactylus</i>	Silky Anteater	8700000	1.39	1.41	1.32	1.45	1.17	0.9	0.98	0.97	0.98	0.98	0.89	0.82
<i>Cynomops parvus</i>	Dog-faced Bat	1855000	1.53	3.81	3.23	5.58	3.42	3.68	0.57	0.73	0.88	0.92	0.89	0.64
<i>Dasyprocta azarae</i>	Azara's Agouti	1637500	0.39	0.5	0	0.64	0.85	0.12	0.29	0.26	0	0.34	0.47	0.02
<i>Dasybus sabanicola</i>	Llanos Long-nosed Armadillo	695000	3.25	1.18	0.4	1.4	7.44	3.37	0.46	0.23	0.05	0.29	0.76	0.39
<i>Delomys dorsalis</i>	Striped Atlantic Forest Rat	142500	0.18	0.14	0.33	0.05	0.05	0.26	0.12	0.07	0.09	0.05	0	0.02
<i>Delomys sublineatus</i>	Pallid Atlantic Forest Rat	212500	0.27	0	1.72	0.18	1.05	0.39	0.08	0	0.08	0.02	0.26	0.01
<i>Eptesicus diminutus</i>	Diminutive Serotine	3152500	1.04	0.45	0.83	0.79	0.56	0.63	0.51	0.34	0.49	0.54	0.4	0.32
<i>Eptesicus fuscus</i>	Big Brown Bat	12362500	1.32	1.13	1.55	1.5	1.18	1.34	0.9	0.83	0.92	0.94	0.86	0.87
<i>Heteromys anomalus</i>	Trinidad Spiny Pocket Mouse	592500	4.04	15.59	15.08	17.14	2.83	7.92	0.49	0.68	0.78	0.77	0.38	0.46
<i>Histiotus macrotus</i>	Big-eared Brown Bat	2215000	0.97	0.8	1.07	1.07	0.57	1.07	0.55	0.54	0.61	0.75	0.42	0.58
<i>Hydrochaeris hydrochaeris</i>	Capybara	13105000	1.12	1.22	1.12	1.05	1.24	1.06	0.94	0.99	0.94	0.94	0.98	0.93
<i>Leopardus pardalis</i>	Ocelot	15232500	1.12	1.11	1.17	1.12	1.31	0.98	0.99	0.98	0.99	0.99	0.92	0.94
<i>Lepus alleni</i>	Antelope Jackrabbit	250000	3.2	5.75	1.03	3.79	1.47	3.59	0.85	0.55	0.05	0.6	0.54	0.72
<i>Lepus townsendii</i>	White-tailed Jackrabbit	3465000	1.52	0.6	1.72	1.14	0.94	1.24	0.73	0.54	0.71	0.72	0.59	0.89
<i>Lichonycteris obscura</i>	Dark Long-tongued Bat	7737500	1.17	1.26	1.36	1.36	1.06	0.86	0.97	0.94	0.97	0.96	0.89	0.78
<i>Lonchophylla hesperia</i>	Western Nectar Bat	227500	0.18	0	2.93	0.02	0.16	3.49	0	0	0.09	0.02	0.03	0.21
<i>Lonchorhina orinocensis</i>	Orinoco Sword-nosed Bat	262500	9.93	0.98	17.76	0.62	1.97	1.79	0.43	0.28	0.56	0.07	0.43	0.38
<i>Lyncodon patagonicus</i>	Patagonian Weasel	1070000	0.93	0.56	0.94	0.72	1.77	1.69	0.44	0.41	0.5	0.56	0.64	0.32
<i>Marmosa robinsoni</i>	Robinson's Mouse Opossum	765000	6.85	2.82	12.44	11.6	4.67	10.93	0.75	0.43	0.79	0.8	0.58	0.64
<i>Marmosops noctivagus</i>	White-bellied Slender Mouse Opossum	1825000	0.47	0.61	0.2	0.75	1.79	0.26	0.3	0.37	0.1	0.43	0.64	0.13
<i>Marmosops parvidens</i>	Delicate Slender Mouse Opossum	2282500	1.17	0.69	1.33	0.98	1.83	0.1	0.23	0.26	0.35	0.25	0.63	0.02
<i>Martes pennanti</i>	Fisher	3455000	1.43	1.27	1.51	1.25	0.91	0.83	0.82	0.75	0.83	0.71	0.51	0.47
<i>Megasorex gigas</i>	Mexican Shrew	155000	0.6	0	3.82	2.31	1.42	6.58	0.1	0	0.02	0.34	0.42	0.16
<i>Mephitis macroura</i>	Hooded Skunk	1832500	1.18	0.53	0.81	1.19	2.21	1.82	0.62	0.33	0.46	0.64	0.74	0.67
<i>Micronycteris hirsuta</i>	Hairy Big-eared Bat	4282500	1.84	2.03	2.2	1.91	1.69	0.79	0.95	0.87	0.95	0.88	0.92	0.46
<i>Microtus oeconomus</i>	Tundra Vole	2352500	0.81	1.1	1.52	1.18	1.52	1.77	0.44	0.46	0.42	0.55	0.47	0.66
<i>Microtus pinetorum</i>	Woodland Vole	2767500	1.27	1.18	1.42	1.23	1.49	0.89	0.93	0.92	0.97	0.92	0.95	0.83
<i>Mustela frenata</i>	Long-tailed Weasel	12200000	1.11	0.8	1.09	2.03	1.09	1.06	0.8	0.65	0.76	0.94	0.69	0.76
<i>Myoprocta acouchy</i>	Red Acouchy	1300000	1.91	1.08	1.67	1.27	4.29	0.57	0.77	0.37	0.28	0.25	0.93	0.02
<i>Myotis evotis</i>	Long-eared Myotis	3115000	1.12	0.79	1.04	1.01	0.8	1.32	0.75	0.69	0.75	0.85	0.68	0.77

<i>Myotis levis</i>	Yellowish Myotis	2900000	0.86	0.52	1.25	0.72	0.99	1.06	0.39	0.38	0.41	0.55	0.5	0.59
<i>Myotis ruber</i>	Red Myotis	1725000	0.61	0.33	0.59	0.4	0.36	0.1	0.46	0.29	0.45	0.31	0.23	0.04
<i>Nasuella olivacea</i>	Mountain Coati	210000	0.74	32.48	21.83	35.04	0	17.68	0.25	0.3	0.43	0.29	0	0.36
<i>Necomys lasiurus</i>	Hairy-tailed Bolo Mouse	5395000	0.87	1.28	0.89	0.61	1.62	1.25	0.56	0.76	0.52	0.4	0.86	0.67
<i>Neotoma goldmani</i>	Goldman's Woodrat	175000	0.3	0.64	0	0.67	5.07	0.61	0.17	0.23	0	0.43	0.83	0.14
<i>Nyctinomops femorosaccus</i>	Pocketed Free-tailed Bat	1132500	1.7	0.6	1.97	1.29	2.21	3.11	0.84	0.41	0.7	0.62	0.78	0.89
<i>Oecomys speciosus</i>	Arboreal Rice Rat	185000	0.35	1.43	0.38	0.46	10.62	6.86	0.12	0.05	0.11	0.04	0.85	0.15
<i>Oryzomys angouya</i>	Rice Rat	1142500	1.62	0.28	3.17	0.96	1.09	0.88	0.38	0.2	0.56	0.38	0.21	0.23
<i>Oryzomys rostratus</i>	Long-nosed Rice Rat	370000	3.26	0.83	0.89	2.36	0.35	3.06	0.62	0.11	0.03	0.3	0.08	0.34
<i>Oryzomys yunganus</i>	Yungas Rice Rat	5302500	1.56	0.96	1.61	0.87	1.78	0.51	0.9	0.67	0.9	0.54	0.96	0.37
<i>Oxymycterus rufus</i>	Red Hociucudo	1395000	0.96	0.3	0.04	0.43	0.62	0.44	0.28	0.23	0.01	0.34	0.3	0.24
<i>Peromyscus levipes</i>	Nimble-footed Mouse	582500	1.28	0.53	3.73	6.76	0.01	4.36	0.5	0.26	0.28	0.7	0	0.42
<i>Peromyscus polionotus</i>	Oldfield Mouse	425000	0.33	0.39	0.25	0.49	3.23	0.05	0.21	0.12	0.08	0.18	0.79	0.01
<i>Platyrrhinus helleri</i>	Heller's Broad-nosed Bat	10765000	1.06	0.99	0.96	1.23	1.26	0.83	0.93	0.84	0.84	0.97	0.92	0.77
<i>Proechimys cayennensis</i>	Cayenne Spiny Rat	3030000	0.7	1.39	0.44	1.58	2.15	0.88	0.24	0.68	0.15	0.78	0.9	0.18
<i>Proechimys oris</i>	Para Spiny Rat	225000	0.12	0	0.04	0	1.54	0.5	0	0	0	0	0	0
<i>Proechimys roberti</i>	Spiny Rat	1077500	0.3	0.82	2.79	0.86	1.13	1.03	0.17	0.5	0	0.5	0.56	0.02
<i>Pteronotus davyi</i>	Davy's Naked-backed Bat	4062500	1.3	2.42	2.82	3.32	2.57	1.58	0.61	0.73	0.83	0.94	0.86	0.57
<i>Rhogeessa tumida</i>	Black-winged Little Yellow Bat	7637500	1.48	1.38	1.58	1.76	1.48	1.1	0.97	0.94	0.96	0.99	0.94	0.85
<i>Saccopteryx gymnura</i>	Amazonian Sac-winged Bat	615000	0.09	0.7	0.38	0.96	1.58	1.26	0	0.11	0	0.18	0.23	0.11
<i>Scapanus latimanus</i>	Broad-footed Mole	337500	1.39	0.67	2.78	1.1	1.01	2.93	0.46	0.44	0.49	0.61	0.4	0.96
<i>Sciurus aestuans</i>	Guianan Squirrel	6922500	0.5	0.62	0.82	0.69	1.29	1.01	0.32	0.39	0.4	0.45	0.81	0.44
<i>Sciurus niger</i>	Eastern Fox Squirrel	4307500	1.56	1.15	1.45	1.52	1.52	0.91	0.99	0.86	0.96	0.96	0.96	0.75
<i>Scotinomys teguina</i>	Alston's Brown Mouse	207500	0.33	--	0.43	0.24	0.19	3.87	0.01	--	0.01	0.04	0	0.17
<i>Sigmodon arizonae</i>	Arizona Cotton Rat	347500	1.68	1.89	1.78	1.37	2.4	1.76	0.73	0.49	0.36	0.58	0.57	0.73
<i>Sorex dispar</i>	Long-tailed Shrew	327500	1.09	0.89	2.45	1.56	0.61	0.4	0.41	0.29	0.59	0.5	0.1	0.14
<i>Sorex trowbridgii</i>	Trowbridge's Shrew	402500	1.1	0.4	0.63	0.84	2.45	1.8	0.58	0.27	0.42	0.55	0.88	0.75
<i>Speothos venaticus</i>	Bush Dog	10617500	1.05	1.11	1.19	1.23	1.32	0.78	0.83	0.89	0.91	0.93	0.94	0.67
<i>Spermophilus elegans</i>	Wyoming Ground Squirrel	272500	0.6	0.23	0.66	0.17	0.39	3.41	0.29	0.1	0.18	0.06	0.15	0.69
<i>Sturnira magna</i>	Greater Yellow-shouldered Bat	1470000	0.27	0.53	0.73	1.04	0.6	0.84	0.08	0.22	0.35	0.49	0.34	0.32
<i>Sturnira nana</i>	Lesser Yellow-shouldered Bat	137500	1.51	0.27	0.73	0.75	1.25	1.36	0.38	0.04	0.09	0.13	0.22	0.16
<i>Tamias rufus</i>	Hopi Chipmunk	140000	0.09	0	1.43	0.02	0.2	6.09	0	0	0.07	0	0	0.54

<i>Tamias umbrinus</i>	Uinta Chipmunk	287500	1.57	0.1	2.09	0.17	0.1	4.63	0.23	0.05	0.23	0.05	0.02	0.61
<i>Tamiasciurus hudsonicus</i>	Red Squirrel	10217500	1.01	1.05	1.02	1.06	1.2	1.19	0.85	0.89	0.87	0.89	0.9	0.94
<i>Thomomys bottae</i>	Botta's Pocket Gopher	1885000	1.81	1.11	1.75	1.66	1.56	2.13	0.84	0.64	0.87	0.84	0.67	0.85
<i>Tonatia saurophila</i>	Stripe-headed Round-eared Bat	7115000	1.68	1.46	1.65	1.52	1.35	1.18	0.98	0.93	0.98	0.96	0.89	0.87
<i>Uroderma bilobatum</i>	Tent-making Bat	12600000	1.02	1.12	0.99	1.14	1.08	0.88	0.95	0.96	0.94	0.99	0.98	0.83
<i>Vampyressa bidens</i>	Bidentate Yellow-eared Bat	6682500	1.27	0.99	0.64	0.77	1.01	0.51	0.97	0.81	0.57	0.5	0.84	0.46
<i>Zaedyus pichiy</i>	Pichi	1475000	0.76	0.61	0.78	0.64	0.9	1.09	0.52	0.43	0.56	0.56	0.53	0.6